A Turn Detection Algorithm in a Wearable Gait Rehabilitation **Application for Lower-Limb Prosthetic Users**

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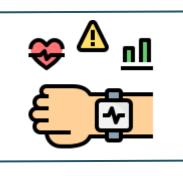
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Background



Lower-limb prosthetic users (LLPUs) undergo gait rehabilitation to increase symmetry between limbs during gait

Wearable sensors can be used to monitor walking and supplement gait rehabilitation





Gait detection **algorithms** are needed so the system is usable **outside of the clinic**

Real-time recognition of activities like turns would allow for an accurate measure of gait in unpredictable community settings





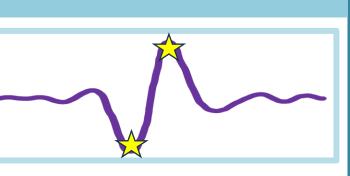
Data Collection:

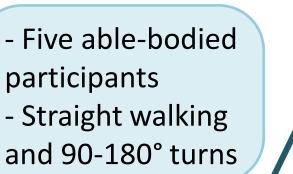
Objective

Create a **robust algorithm** that correctly detects the start and end points of turns during gait

Methods

Python Algorithm: detects turns from angular velocity extrema





Elastic ankle strap Secures sensor to ankle via Velcro

Inertial measurement unit (IMU) sensor

Measures and records tri-axial acceleration and angular velocity data

A wearable rehabilitation system that identifies turns allows for lower-limb prosthetic users to monitor and improve their gait outside of clinical settings



Scan for a project demo video

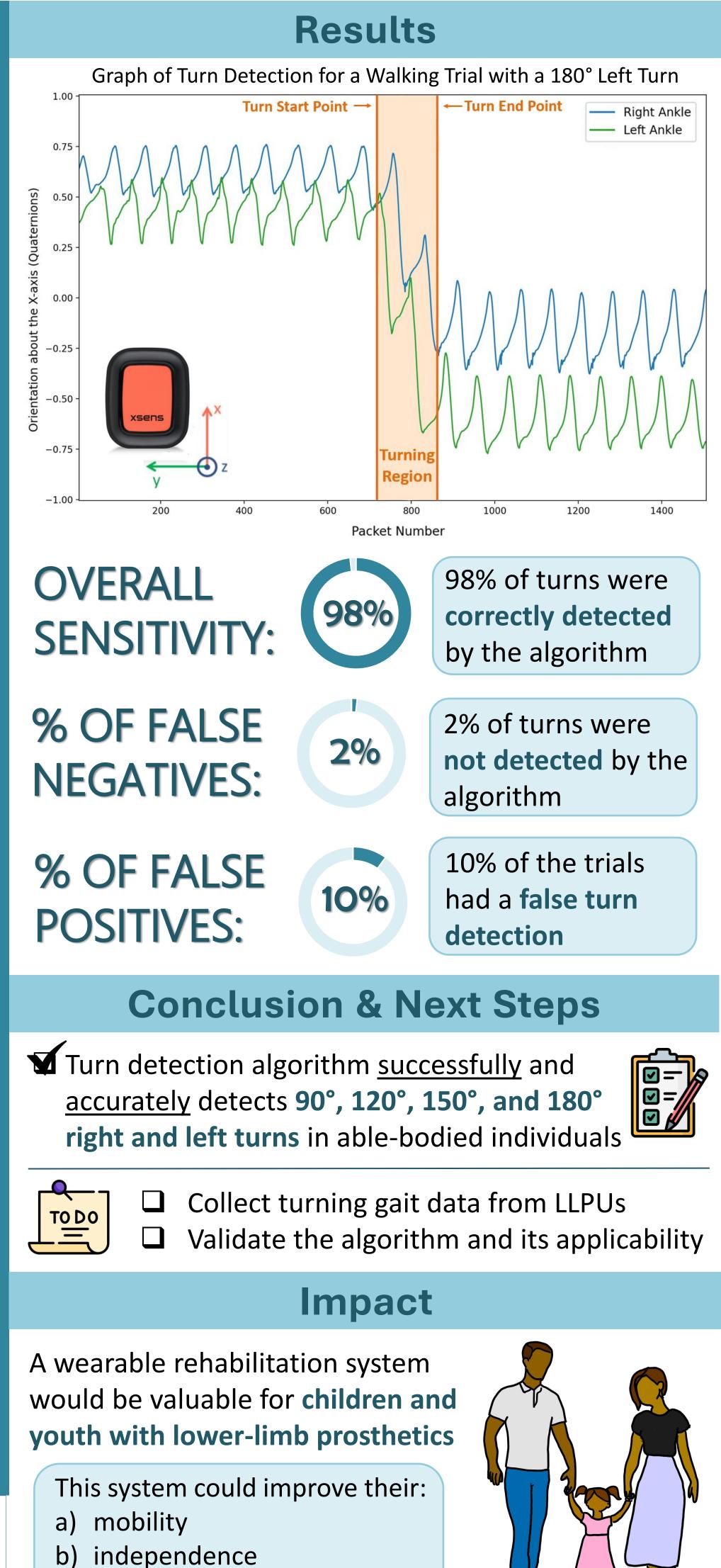








*This research study was approved by the Research Ethics Board at Holland Bloorview Kids Rehabilitation Hospital (REB-0448)



- c) musculoskeletal health